

# COMPRESSED VOLUMETRIC HEATMAPS FOR MULTI-PERSON 3D POSE ESTIMATION

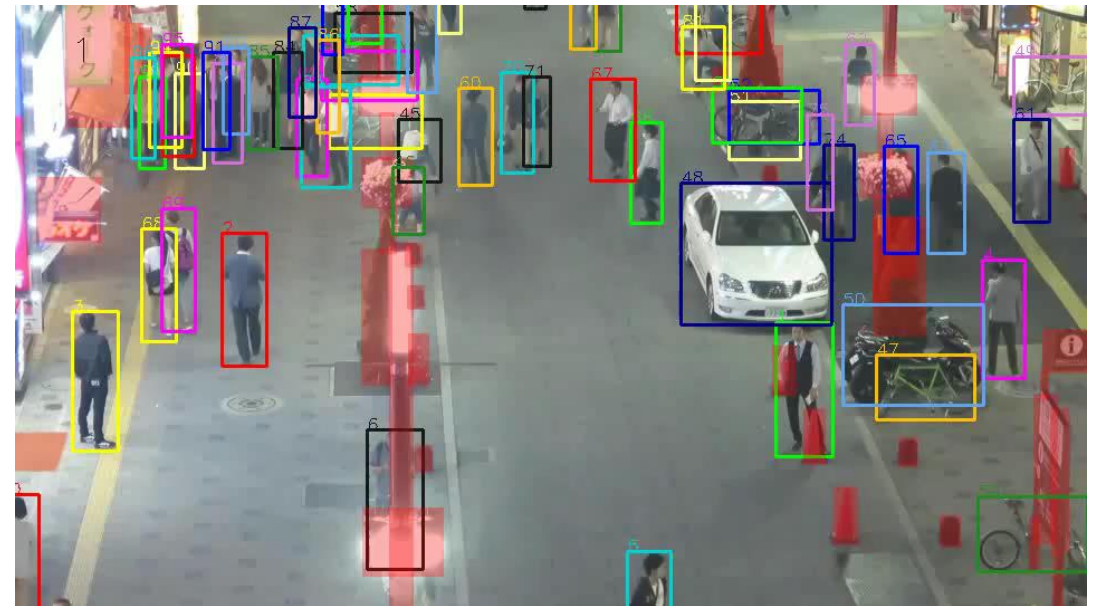
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# PEOPLE TRACKING

- It is defined as the problem of estimating the trajectory of multiple people in an image plane as it moves around a scene.
- **We are addressing a 3D problem using 2D data**
- It's hard to annotate 3D data, especially in surveillance scenarios



# JTA DATASET

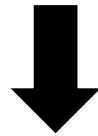
- Let's utilize a videogame:
  - Free Annotation
  - No errors
  - Photorealism
- 512 Full HD videos 30s long
- 10M people with 3D annotation





# 3D POSE ESTIMATION

- Single person -> Coordinate regression
- Multi person -> People Detection + Coordinate regression

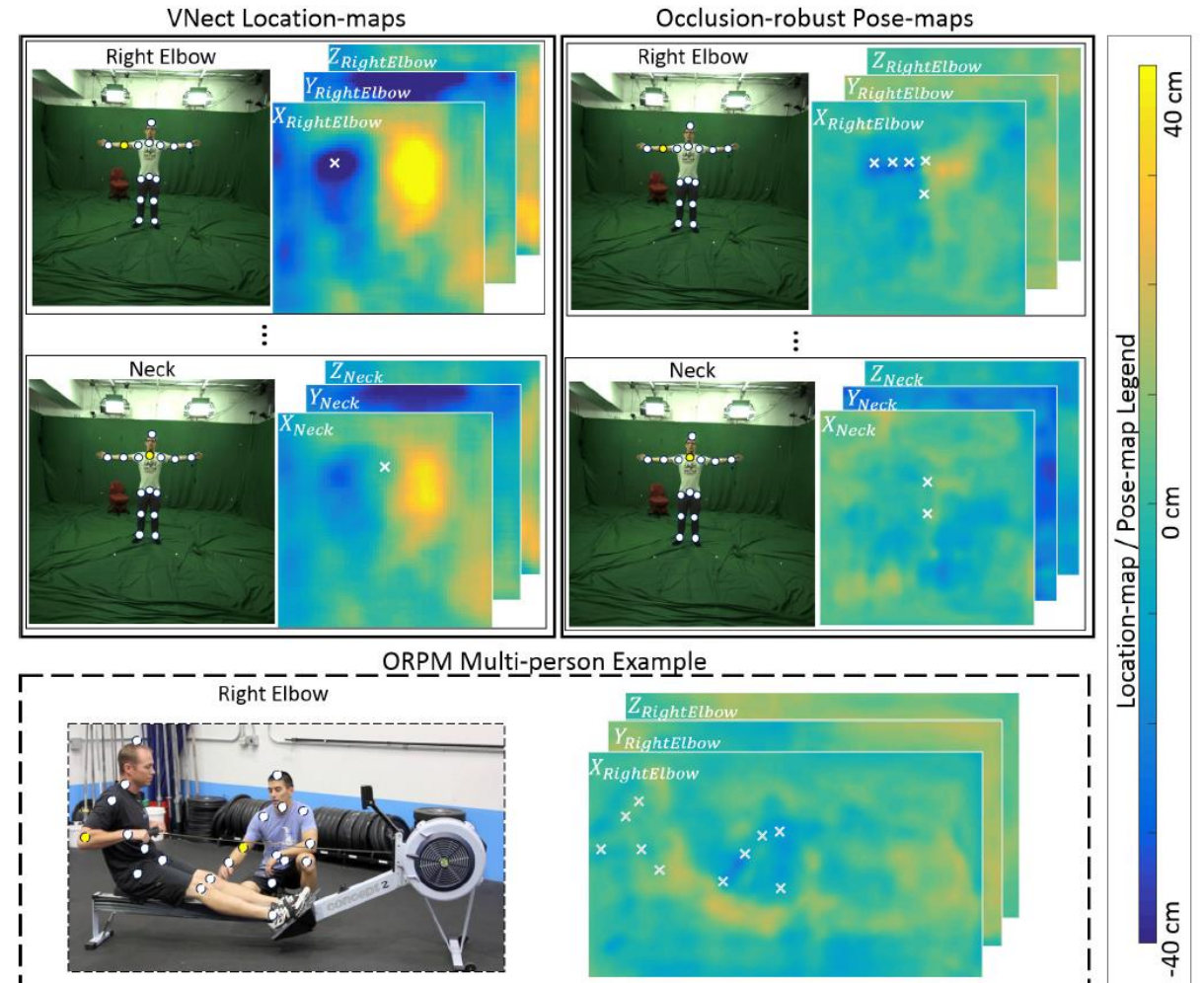


This approach does not scale with the number of people!

We need a bottom-up approach.

# BOTTOM-UP 3D POSE ESTIMATION

- Few methods in literature
- Location Maps are not suitable in surveillance
- What about 2D pose estimation?



# 2D POSE ESTIMATION

- For 2D pose estimation Heatmaps are the best choice
- What about 3D heatmaps?

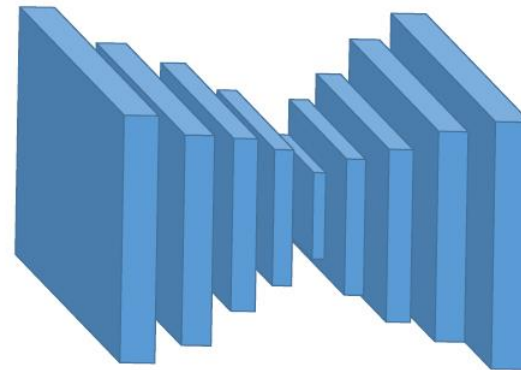


# VOLUMETRIC HEATMAPS

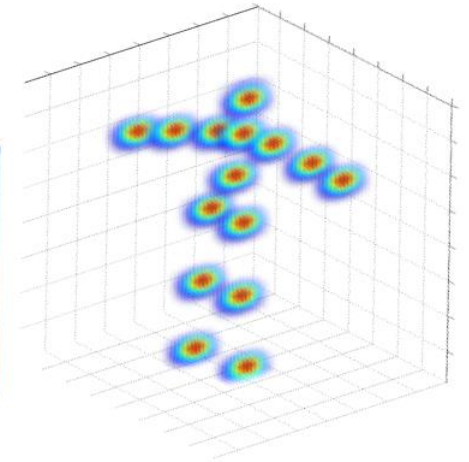
- Only for single person
- Memory and computational demanding
- Sparse signal
- Some compromise:
  - low resolution heatmaps that introduce quantization errors
  - complex training strategies that involve coarse-to-fine predictions



Image



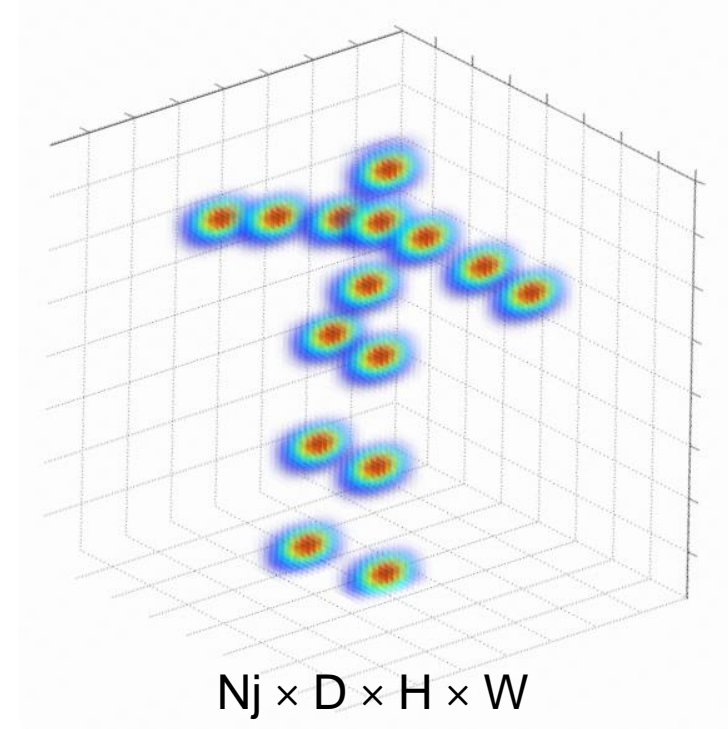
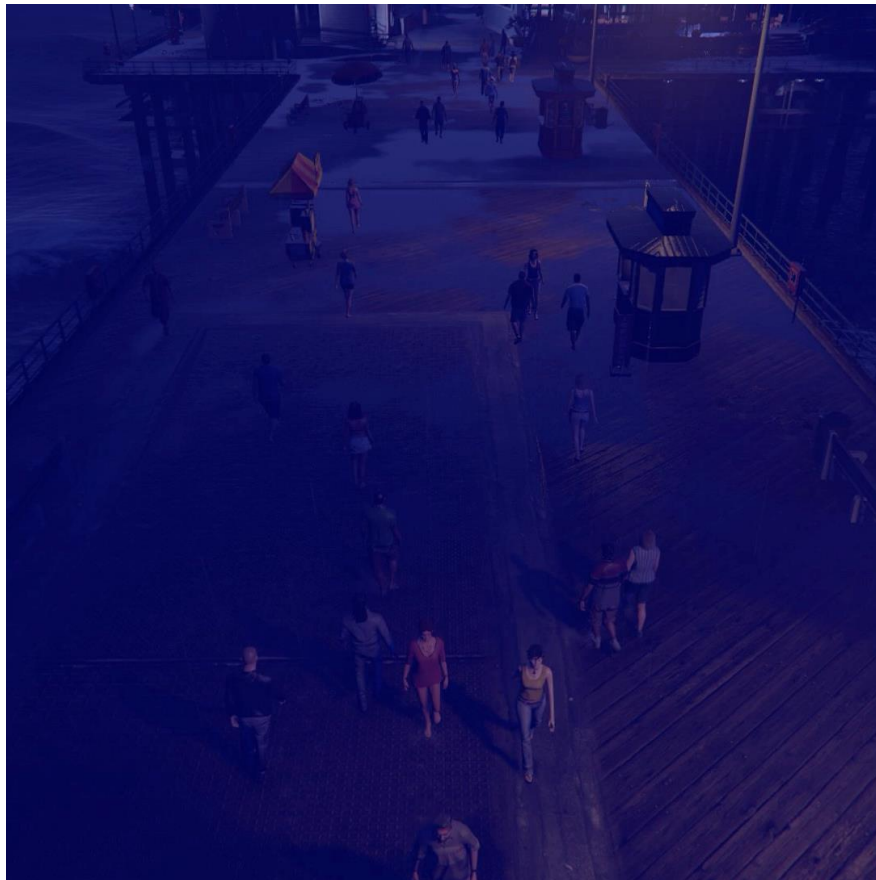
ConvNet



Volumetric Output



# VOLUMETRIC HEATMAPS FOR MULTI PERSON



Full HD images with stride  
8 and 10cm quantization

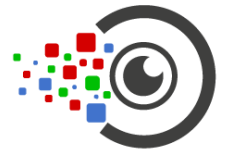
$14 \times 1000 \times 128 \times 240$

# COMPRESSION

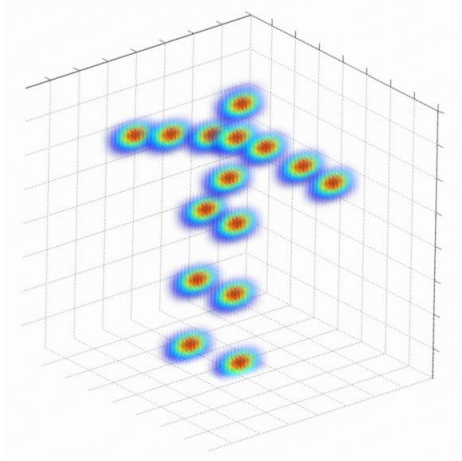
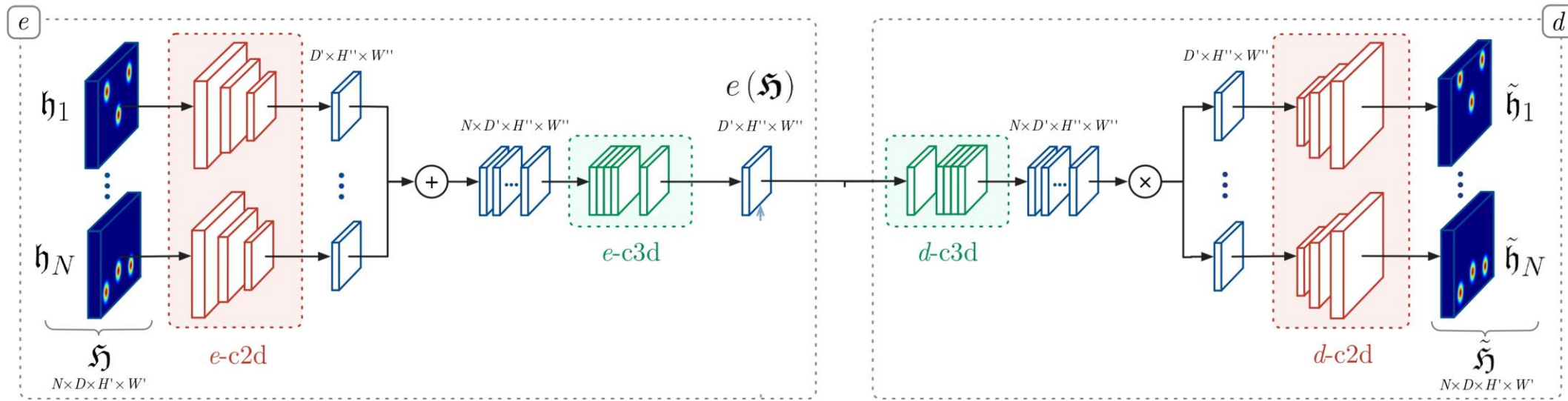


- Let's compress the Volumetric Heatmaps!
- Sparse data representation -> easy to compress
- RLE?
- Deep compression?

# AUTOENCODER

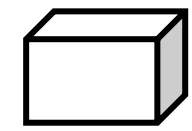


AImage<sup>Lab</sup>



$14 \times 316 \times 128 \times 240$

~7000 smaller



$1 \times 39 \times 17 \times 30$

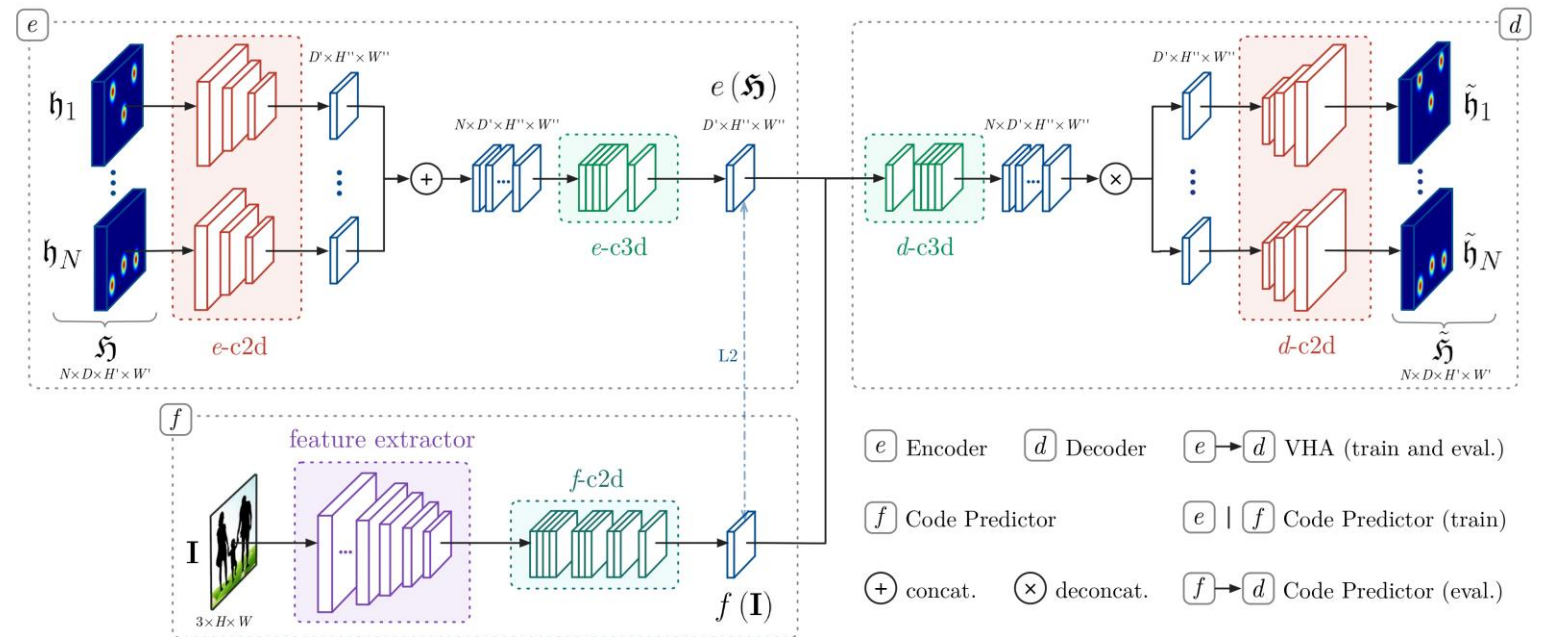
# OUR SOLUTION: THE LOCO APPROACH

We propose a simple method that maps high-resolution volumetric heatmaps to a **compact** and **more tractable** representation.

To this end, we use an **Autoencoder** to compress those **Volumetric Heatmaps** into a **Code** that must:

- **preserve** the gaussian **peaks** at every joint location
- be **smaller** w.r.t. the full resolution heatmaps

This representation enables, for the **very first** time, the use of volumetric heatmaps to tackle 3D Human Pose Estimation in a bottom-up fashion.



# COMPRESSION LEVELS

model	bottleneck size	F1 on JTA		
		@0vx	@1vx	@2vx
VHA <sup>(1)</sup>	$\frac{D}{2} \times \frac{H'}{2} \times \frac{W'}{2}$	97.1	98.4	98.5
VHA <sup>(2)</sup>	$\frac{D}{4} \times \frac{H'}{4} \times \frac{W'}{4}$	92.5	97.0	97.1
VHA <sup>(3)</sup>	$\frac{D}{8} \times \frac{H'}{8} \times \frac{W'}{8}$	56.5	90.3	92.9

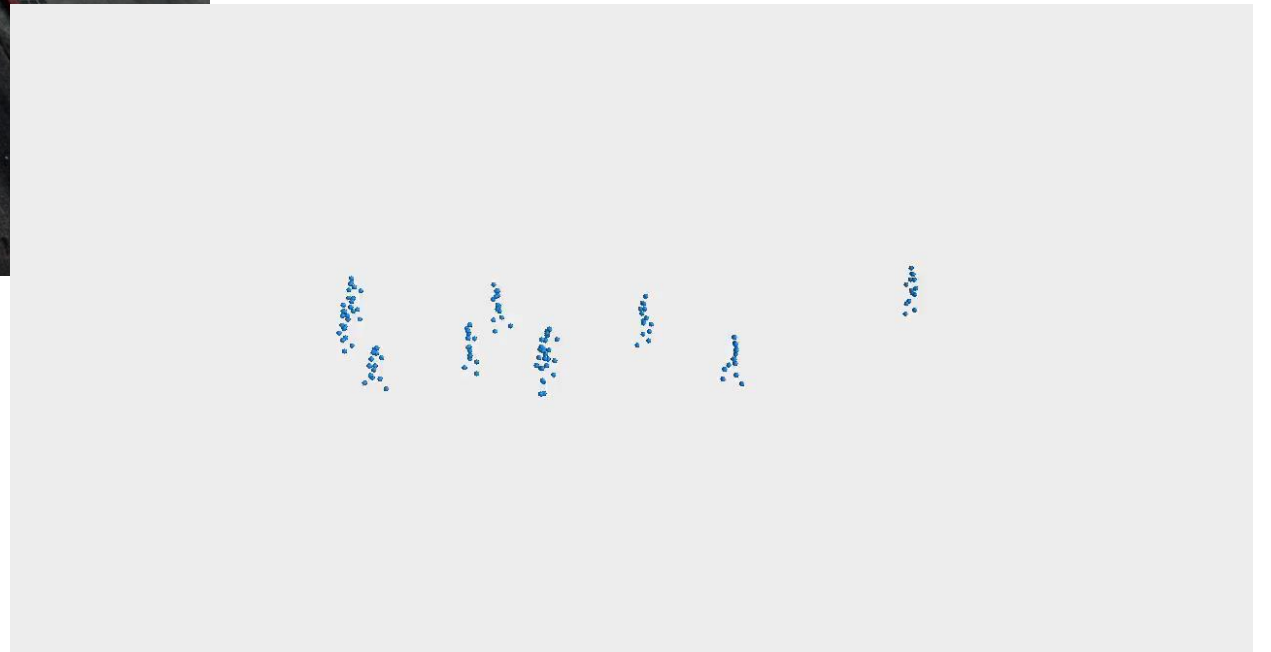
# QUANTITATIVE RESULTS

	PR	RE	F1	PR	RE	F1	PR	RE	F1
	@0.4 m			@0.8 m			@1.2 m		
Location Maps [21, 22]	5.80	5.33	5.42	24.06	21.65	22.29	41.43	36.96	38.26
Location Maps [21, 22] + ref. [33] + [19]	5.82	5.89	5.77	23.28	23.51	23.08	38.85	39.17	38.49
	<b>75.88</b>	28.36	39.14	<b>92.85</b>	34.17	47.38	<b>96.33</b>	35.33	49.03
Uncompr. Volumetric Heatmaps	25.37	24.40	24.47	45.40	43.11	43.51	55.55	52.44	53.08
LoCO <sup>(1)</sup>	48.10	42.73	44.76	65.63	58.58	61.24	72.44	64.84	67.70
LoCO <sup>(1)</sup> +.	49.37	43.45	45.73	66.87	59.02	62.02	73.54	65.07	68.29
LoCO <sup>(2)</sup>	54.76	46.94	50.13	70.67	60.48	64.62	77.00	65.92	70.40
LoCO <sup>(2)</sup> +.	55.37	<b>47.84</b>	<b>50.82</b>	70.63	<b>60.94</b>	<b>64.76</b>	76.81	<b>66.31</b>	<b>70.44</b>
LoCO <sup>(3)</sup>	48.18	41.97	44.49	66.96	58.22	61.77	74.43	64.71	68.65
LoCO <sup>(3)</sup> +.	49.15	42.84	45.36	67.16	58.45	61.92	74.39	64.76	68.57
GT Location Maps [21, 22]	76.07	64.83	69.59	76.07	64.83	69.59	76.07	64.83	69.59
GT Volumetric Heatmaps	99.96	99.96	99.96	99.99	99.99	99.99	99.99	99.99	99.99

# QUALITATIVE RESULTS

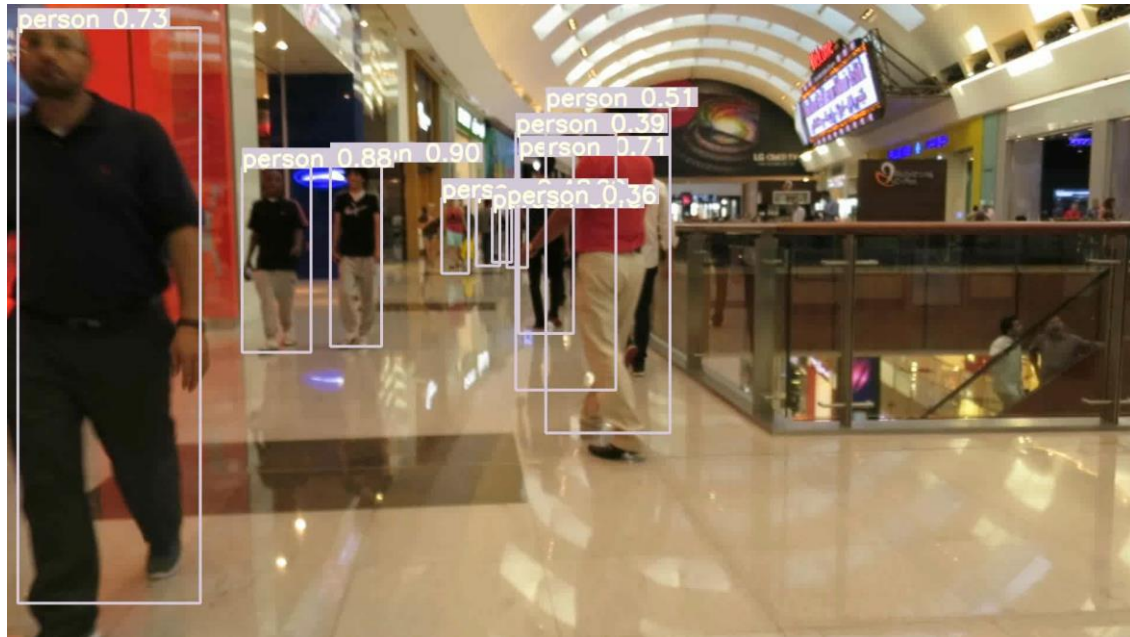


# QUALITATIVE RESULTS





# DOES GTA GENERALIZE TO REAL WORLD?



For people detection, YES!

**THANK YOU!**

If you have questions, please contact me

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